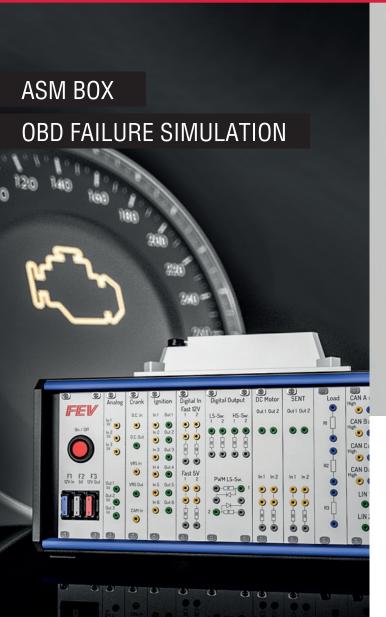
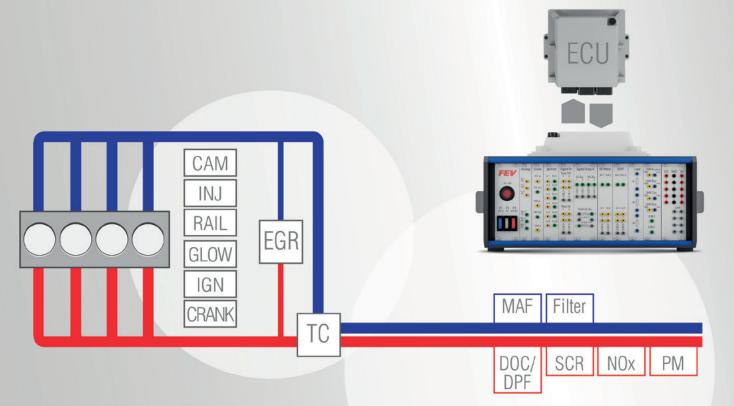
# CONTACT TOPEXPERT ASM BOX

# ONE SOLUTION COVERING ALL SIGNAL MANIPULATION PATTERN









The ASM Box allows efficient verification of PVE and OBD calibration via electrical manipulation of actuator and sensor signals, especially for U.S. homologation with government mode in addition to the common user mode. Because no faulty hardware is required for failure generation it achieves a cost savings of at least 20 percent in typical use cases. Using the ASM Box for automated drifting of sensor signals for robustness testing improves the quality as well as the efficiency.

FEV's ASM Box is based on a model-based automotive RCP system. With predefined Simulink® models, efficient and fast manipulation of any engine component can be realized. The standard models can be easily customized to satisfy individual manipulation needs. In the case of calibration tasks, it is possible to use a calibration tool with XCP support to control the model behavior and simultaneously handle ECU labels and signals. In the case of homologation, the ASM Box offers a user friendly GUI with the possibility of controlling the system via WiFi and LAN.



### Fields of application

Homologation

Robustness Evaluation Production
Vehicle Evaluation



### Learn more about the ASM Box:

FEV GmbH

Mr. Rafael Dziadek

Neuenhofstraße 181

52078 Aachen · Germany phone +49 241 5689-838

Mail: calibrationmethods@fev.com

www.fev.com/topexpert



### BENEFITS AT A GLANCE

- > Easy realization of complex fuel system manipulation including:
- > Injection cut-off
- > Changing start of injection and injection duration
- > Applicable for each partial injection
- > Ignition turn-off
- > Convenient handling by versatile break-out box
- > Full flexibility by failure pattern development in MATLAB/Simulink®
- > Includes a base set of failure models
- > XCP access for comfortable parametrization of failure models
- > Oxygen sensor signal manipulation
- > Control system manipulation e.g. SENT, LIN and CAN



ASM box with ruggedly designed breakout box.

Ease of operability through government mode.

# Actuators Sensors MATLAB® SIMULINK® Flash CAN/XCP ATI VISION ETAS INCA Vector CAN/Appe

## SUMMARY OF REALIZED SIGNAL MANIPULATION PATTERNS

### The following signal manipulation patterns have been successfully realized with the ASM Box:

- > CAN protocol for NOx sensors and PM sensors as well as manipulation of any message on a powertrain CAN bus without interfering with other messages.
- > For SENT protocol the feedback message of the Delta P sensor, EGR-LF and MAF sensor signals have been manipulated.
- > Successful manipulation via PWM signals of EGR-HF, AIR flap, MAF sensors, ignition and VVT actuators.
- > Any temperature sensor and rail pressure sensor via analog signals.
- > Oxygen sensor manipulation for CJ135 has been realized for LSF, LSU4.9, LSU5.1 and LSU-ADV.
- > One of the highlights is injection manipulation for both Solenoid and Piezo injectors. The common misfire patterns are realized as well as complex scenarios such as shifting the start and end of injection.

# ASM BOX IS AVAILABLE IN THREE VARIATIONS

|                                     | ASM BOX        | ASM BOX COMPACT | ASM BOX<br>OXYGEN |
|-------------------------------------|----------------|-----------------|-------------------|
| Analog I/O                          | 3/3            | 3/3             | 3/3               |
| PWM I/O                             | 4/6            | 3/3             | 3/3               |
| DC motor I/O                        | 2/2            | <b>3</b>        | 8                 |
| SENT I/O                            | 2/2            | 2/2             | 2/2               |
| Speed sensor (inductive) I/O        | <b>1</b> /1    | 8               | 8                 |
| Solenoid injectors I/O              | 6/6            | 8               | <b>3</b>          |
| Ignition signal<br>(TTL) I/O        | 6/6            | 8               | <b>©</b>          |
| CAN I/O                             | 4/4            | <b>4/4</b>      | 3/3               |
| LIN I/O                             | <b>(</b> ) 1/1 | <b>(3)</b>      | <b>3</b>          |
| Break-out Box                       |                |                 |                   |
| ASM Box<br>Manipulation Models      | Base set       | optional        | O2 model          |
| ASM Box<br>Model Generation Toolkit |                | optional        | 8                 |
| Cables and plugs                    | optional       | optional        |                   |
| CJ 135 + LSU 5.1 module             | optional       | optional        |                   |

Special configurations on request.

